GNSS Aided Inertial Navigation System Wataridori (INS-00b)



O- Description

- GNSS composite inertial navigation system that combines MEMS gyro/accelerometer and GNSS receiver
- Compared to RLG and FOG type INS, it is less than 1/10 smaller, lighter, low power consumption, and low price and has the same level of performance
- Receive almost all GNSS, GPS/Galileo/GLONASS/BeiDou/QZSS/SBAS
- Switchable automatically between free inertia and GNSS combined inertia based on GNSS signal receiving status and reliability (ex. based on DOP)
- Capable high adaptability and robustness following GNSS receiving condition (changes from moment)

O- Application

Attitude monitoring of air	Inertial navigation system
mobility such as eVTOL	for aerospace and marine
and drone	vehicles
Installed in devices that require highly accurate position information	Mobile device mapping Etc.

• Technical Data		
INS-00b Chai	racteristics	
Navigation Performance	1.5nm/hr(GNSS No Aided), 1.0nm/hr(Aided)	
GNSS Capability	Single Antenna Standard, PPP Capable	
Tracking Satellites	GPS, Galileo, QZSS, GLONASS, BeiDou, SBAS	
Size/Weight	9cm × 8cm × 7cm / 0.75kg	
Supply Voltage	+12VDC(Typ)	
Power Consumption	2W(Max)	
Operating Temperature Range	-45℃ to 75℃ %No condensation	
Cooling	Passive	
Communication Interface	RS422/RS232/UART, others	

Next Generation Model(INS-11) Now on Progress!!

Development will be completed around the 1Q of 2024

INS-11 Characteristics	
Navigation Performance	0.3nm/hr(GNSS No Aided), 0.1nm/hr(Aided)
GNSS Capability	Single Antenna Standard, PPP Capable
Tracking Satellites	GPS, Galileo, QZSS, GLONASS, BeiDou, SBAS
Size/Weight	12cm × 12cm × 10cm / 2kg XInclude mounting flange
Supply Voltage	+12VDC(Typ)
Power Consumption	2W(Max)
Operating Temperature Range	-45℃ to 75℃ %No condensation
Cooling	Passive
Communication Interface	RS422/RS232/UART, others

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